

Thermo Profile Scanner

for tube welding



HKS-Prozesstechnik GmbH

We eye Your welding Quality

The view through the arc into the heat signature



Local heat input is melting and is changing the structure of materials during brazing and welding processes.

The correct heat input and also the undisturbed heat distribution is an important attribute for the evaluation of welding seams.

The human eye can not see heat radiation. The glare of the visible part of an arc is so intense, it will cover up any heat information.

TIG - Arc Heat radiation only Here fore technology is required that can capture the heat information in spite of: - Massive glare of the arc

- Fumes and spatter contaminated environment permanently.

HKS is introducing a device , that fulfills these requirements





Principle of operation ThermoProfilScanner



The Thermoprofilscanner is constantly capturing a thermo profile across the welding seam.

Hereby it is able to fade out the visible light from the arc. A heat image of the welding seam is created by the continues movement of the welding torch.

Technical data:

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- Work distance 15 to 120 mm (special edition 200mm)
- Scan frequency >= 400 Profiles/s and shutter speeds of a single line of 50 μs allowing a resolution of up to 15 m/min (Laser / arc welding) or high frequency of 180 m/min.
- better than 1 mm by speeds up to 20 m/min.
 - Advanced design features allows continuous use in strongly contaminated environment (welding smoke, welding splash, water vapour etc.):
 - ✓ Glass free design
 - ✓ Gas curtain
 - ✓ Anti spatter concept
 - ✓ Integrated water cooling



Extremly robust action directly on the welding torch



The heat signature is captured after solidification of the welding seam, before the seam is cooled of.

Depending on the application this can be 5 mm to 40mm behind the torch.

The sensor can withstand most extreme working conditions and works reliable in great heat, dirt and spatters





The ThermoProfilScanner as component for monitoring system WeldQAS



WeldQAS

Weld monitoring system



Production documentation Extensive representation

and analysis functions

Welding process supervision

Thresholds for warnings and faults

Recognize faults reject

automatic recognition of faulty part and rejection in serial production

Fault output for part marking, ejection and alarm



Design and method of operation

- 1. The Thermoprofilscanner is capturing the temperature over the welding joint and is sending the data to the WeldQAS-device.
- 2. The WeldQAS-device is calculating for each line the attributes of the profile (width and position of the heat field, symmetry and max. temperature.)
- 3. The heat images are displayed simultaneous visually by the WeldQAS, stored and compared with programmed set values.
- 4. By recognizing violations of limit values the unit detecting welding irregularities and there position within the pipe.
- 5. The error signal is generated immediately or can be buffered to mark the defective with a marking spray unit.
- 6. The WeldQAS-device is storing all data pertaining to the pipes, which will be numbered, and can be synchronized with a saw signal.
- 7. The data are stored in a data base and are displayed in a pipe monitor program.



TPS advantages compared to other test methods

Optical offline-method (after welding) (Automatic visualization via laser triangulation)

Principle: Laser is projecting a cut line onto seam, a camera system with image processing unit is evaluating patterns.

In comparison: Use of TPS

> better fault detection of

- Pores
- Penetration faults
- Fusion faults below surface

substantially lower investment costs

> no tact time increase

Eddy current method Principle: Is inducting eddy currents into base material and is processing disturbances in current flow.



In comparison: Use of TPS

better fault detection with

- Seam offset
- insufficient penetration
- (for example due to current deviation up to 50 %)
- small holes
- unsymmetrical edge penetration

> lower Investment costs



New possibilities of seam control





Visual seam inspection Recognition of seam position

Evaluation of metallurgic-thermal processes in the seam

to recognize penetration faults and insufficient fusion along edges

The temperature profiles are processed in **real time**, width, position and symmetry e.t.c are analyzed.

Welding inconsistencies compared to the OK-seam are recognized as deviations within the thermo profiles and will be flagged.

Attributes of the thermo profiles (width, position..) are thought the same way as other parameters, and can be monitored via thresholds or envelopes.



The view *into* the welding seam in creation

The thermo profile is captured after solidification of the welding seam, before it is cooled down. Depending on the application this happens 5 to 50 mm behind the torch.





New possibilities of seam control





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Task

Recognition of visible and invisible welding inconsistencies as holes, pores larger than 1 mm, edge fusion faults and penetration fluctuations.

Recognition of "weld ability" problems with supplied materials.

The existing eddy current detection system does not fulfill requirements.

ThermoProfilScanner

offset to the torch: **40 mm** scan frequency: **100 Hz** resolution: **0,9 mm** working distance: **20-60 mm** purging gas: **3 l/min** welding speed up to **3,5 m/min** water cooling via power source







Work monitor with actual seam evaluation and heat signature

Captured are:

- Welding current,
- Voltage,
- Shield gas amount,
- Band position and -speed



Heat signature of a 6 m tube

From the heat signature the following is calculated:

- Welding seam position
- Width of temperature zone
- Symmetry of heat field
- Cool down characteristic



Special features for seam pipe welding

🕂 F2 Arbeit	en 🝰 F3	Prüfprogram	🚸 F4 <u>A</u> ufzeid	chnur F5 Rohrmonitor Extras 14:09:28 Beenden
				Schließen
12,75 m 📕 🧖 🦟 15,75 m 🔤 🖓 👘				
Zeit	Rohr	Aufz.	Pos.	Bewertung
13:59:01	6	62	149,7 m	
13:53:06	5	61	143,7 m	
13:47:12	4	60	137,7 m	
13:45:42	3	59	131,7 m	
13:39:47	2	58	130,1 m	
13:33:54	1	57	124,1 m	
13:28:00	4137	56	118,1 m	
13:27:17	4136	55	112,0 m	
13:26:17	4135	54	111,3 m	Measurement of the running tube position and
13:20:23	4134	53	110,3 m	allocation wolding faults to wolding position
13:14:29	4133	52	104,3 m	
13:08:35	4132	51	98,2 m	Marking of faulty tube sections, when these
13:02:42	4131	50	92,2 m	reach marking position
12:56:47	4130	49	86,2 m	
12:50:54	4129	48	80,2 m	Data allocation after tube separation to one set
12:44:59	4128	47	74,1 m	of data for each tube including heat images
12:39:05	4127	46	68,1 m	
12:33:11	4126	45	62,1 m	Integrated network functionality
12:27:18	4125	44	56,1 m	
12:21:23	4124	43	50,0 m	

Graphic display of the last 25 tubes in **tube monitor** application



Fault image: Burn trough

CrNi – Band 73*1,0 tube 32mm



Burn through is causing heat jam.

One scan is equivalent to scan width of 0,62 mm.



Fault image: Uneven heat distribution

Steel band 86*1,5 – tube 38 mm



Uneven heat input and penetration fluctuations due to defective band material (Seam appearance – fish scaling)



Fault image: Seam offset / seam position

CrNi - Band 73*1,0 tube 32mm



Such seam offsets causing welding seam to fail when the tube is pressurized.



Example 2 Longitudinal pipe manufacturing TIG/Plasma

Task

Detection of visible and invisible welding irregularities as pores, insufficient sidefusion, defect root penetration and the detection of torch misalignments.

ThermoProfilScanner

offset to the torch: 20 mm scan frequency: 100 Hz resolution: 0,9 mm working distance: 80 mm purging gas: 3 l/min welding speed up to 1,5 m/min water cooling





Fault image: Torch is not in center line of the welding joint. (Seam symmetry)

CrNi - pipe 20*3 mm



An off- center torch position is causing an asymmetric penetration. One fusion edge is melted more than another.

Optical hardly visible, but clearly visible in the heat signature.



Fault image: pores

CrNi - tube 20*3 mm



Hot cracks and pores are represented as "Hotspots" in the heat image. Faults like these are causing a disturbance in the heat conduction and are therefore detectable. These pipes are defective.



Fault image: asymmetric penetration due to a misaligned coil feed.



Optical not visible, here the thermo profile is becoming more and more asymmetric, because of wear and tear or insufficient lubrication on a roller set.

CrNi - tube 20*3 mm



Example 3 High Frequency-Induction Welding (HFI)



Application Data TPS

After running to torch : **100 mm** Working distance: **60 mm** Gas purge Shield gas: **3 l/min** Welding speed **80 m/min** Water cooling Pipe dimensions: **13 x 2,5 mm HFI-Generator 250 kW – conductive HFwelding** Pipes are spooled to coil

Task

- Realizing a set up help for optimal welding parameters based on heat signature
- Recogognition of visible and invisible welding faults, cold joints, and excessive root penetration.
- Color marking faults
- Re-place Eddy Current Detection Systems since these can not detect these faults



Example 3 High Frequency-Induction Welding (HFI)

Detecting cold fusion points



Heat signature when fault through cold fusion joint

When the melting temperature is not reached, the temperature is falling in the joining zones.

The sensor is calculating the heat field width via a set temperature threshold. Cold welding joints can be clearly seen in the diminishing heat field width.

Width of heat filed and learned thresholds values.



Fault image: Torch is not in center line of the welding joint. (Seam symmetry)

CrNi - pipe 20*3 mm



An off- center torch position is causing an asymmetric penetration. One fusion edge is melted more than another.

Optical hardly visible, but clearly visible in the heat signature.



Examples for mounting of the TPS





















Plasma – welding

35 x 3 mm / 3 m/min









TIG – welding / spiral tubes

variable diameters





HFI - welding





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Thank you for your interest.

For further assistance please do not hesitate to contact us:

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